

FIG.1

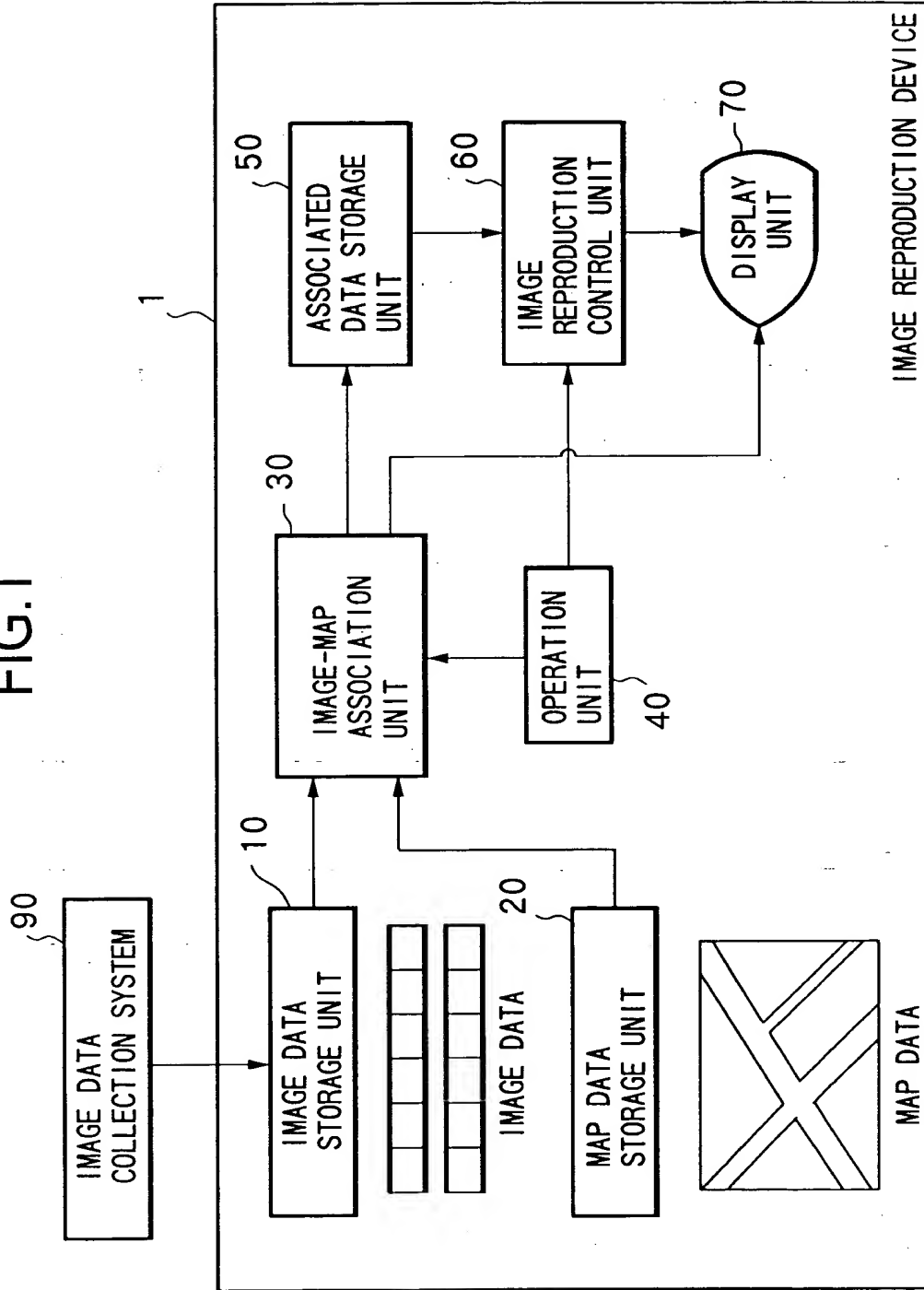


FIG.2

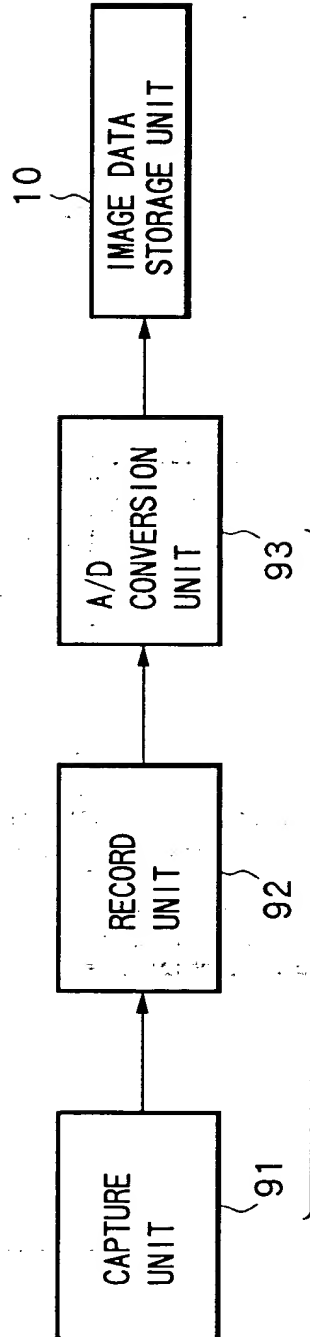


FIG.3

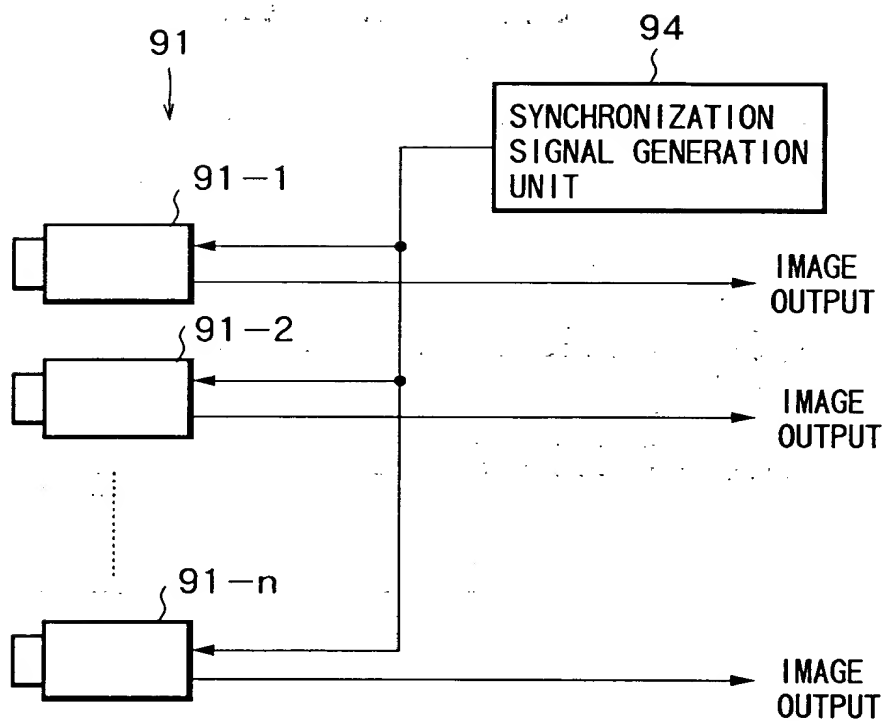


FIG.4

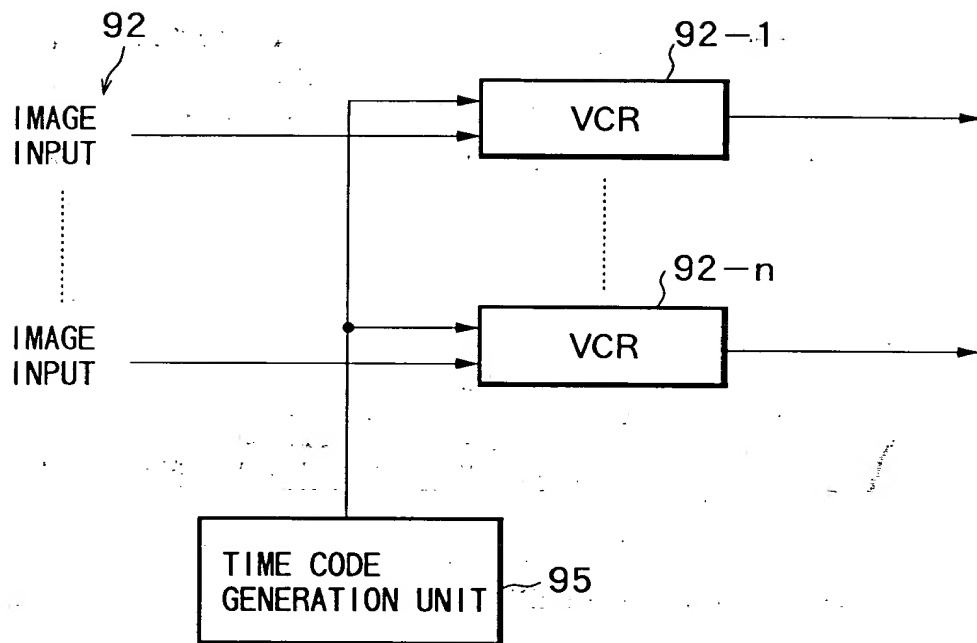
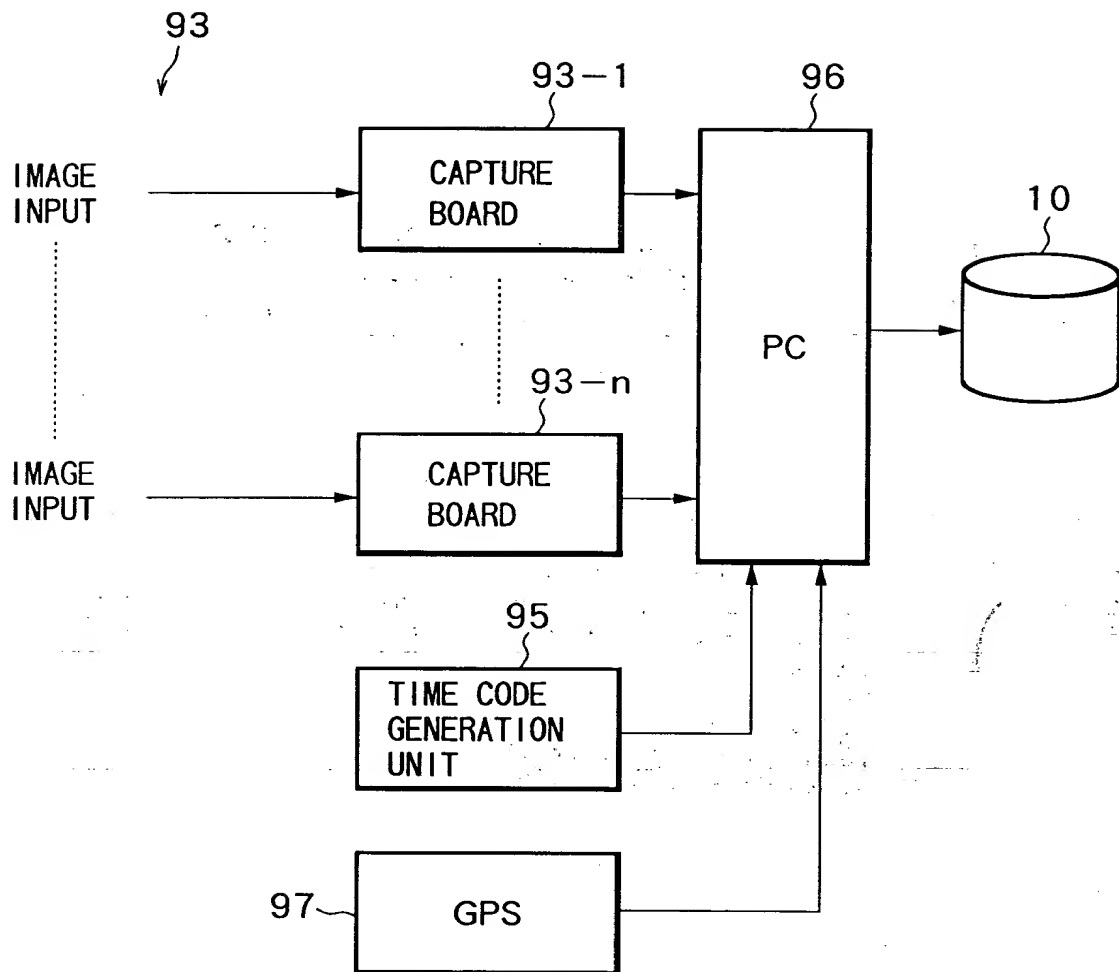


FIG.5



## FIG.6

## POSITION DATA (GPS MEASUREMENT RESULT DATA)

TIME CODE	POSITION( $\theta$ )	POSITION( $\phi$ )
00:00:00:01	135.000	35.000
00:00:00:02	135.002	35.001
00:00:00:03	135.004	35.002
00:00:00:04	135.005	35.002
...	...	...
00:00:00:10	135.010	35.008

## VIDEO DATA

TIME CODE	FRAME NUMBER	FRAME DATA
00:00:00:01	000001	
00:00:00:02	000002	
00:00:00:03	000003	
00:00:00:04	000004	
:	:	
00:00:00:10	000010	

FIG. 7

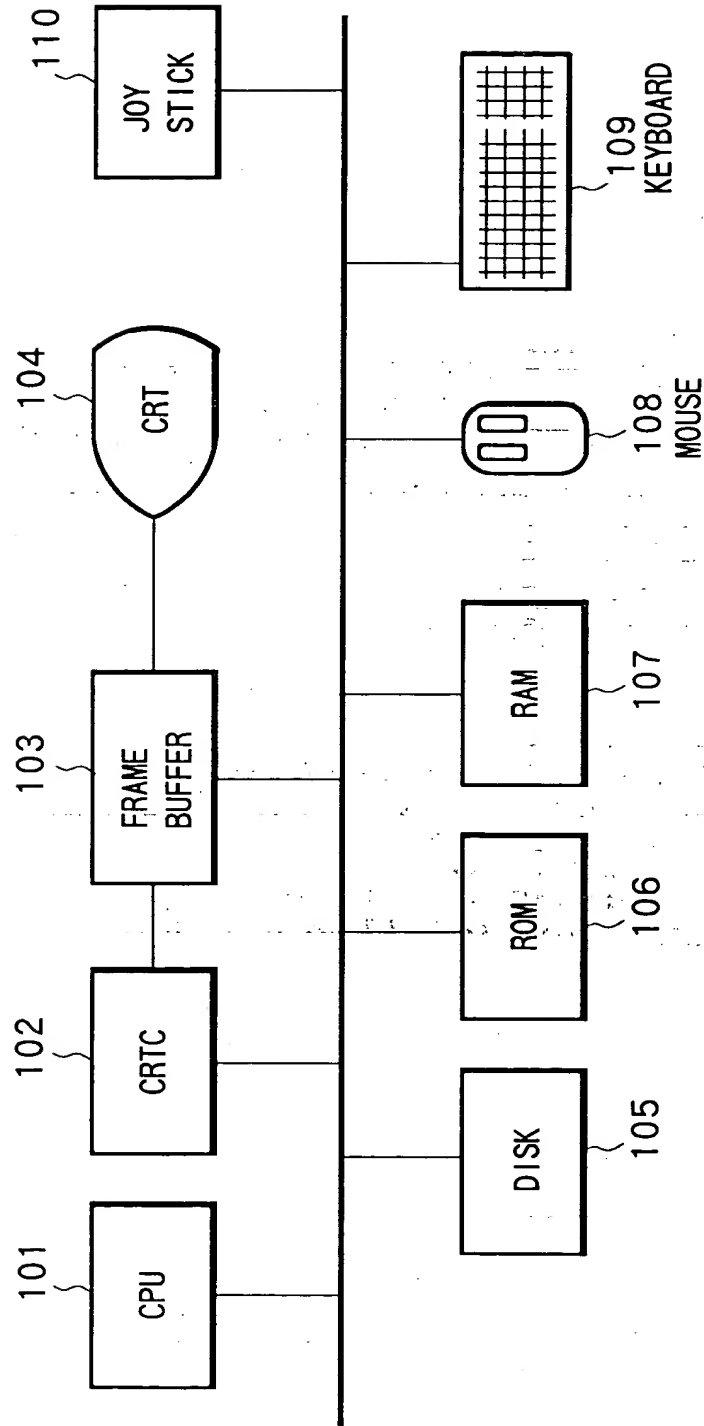


FIG.8

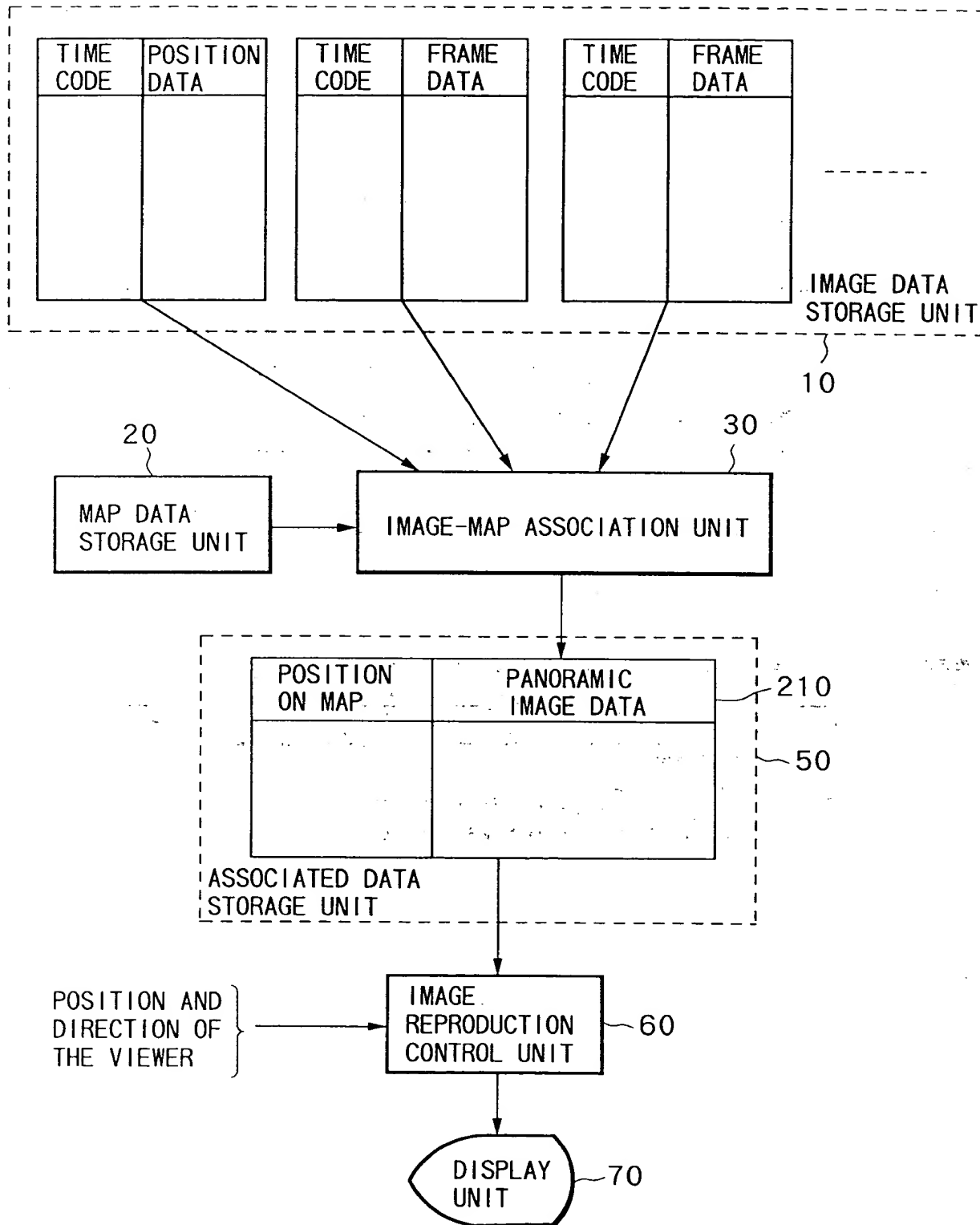




FIG.9

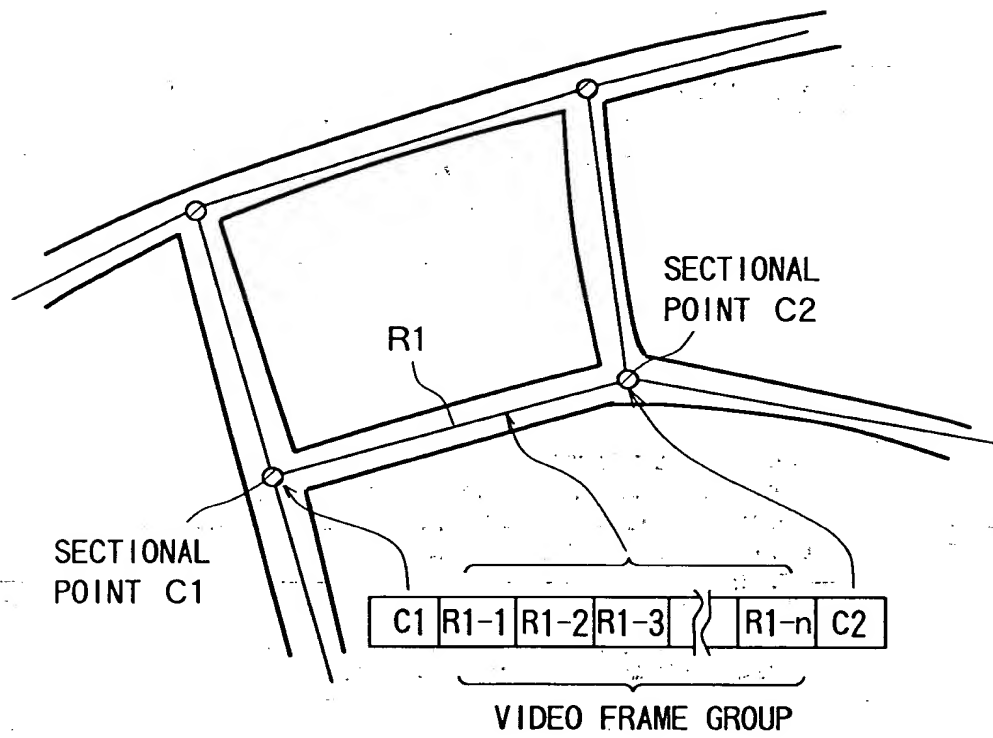


FIG.10

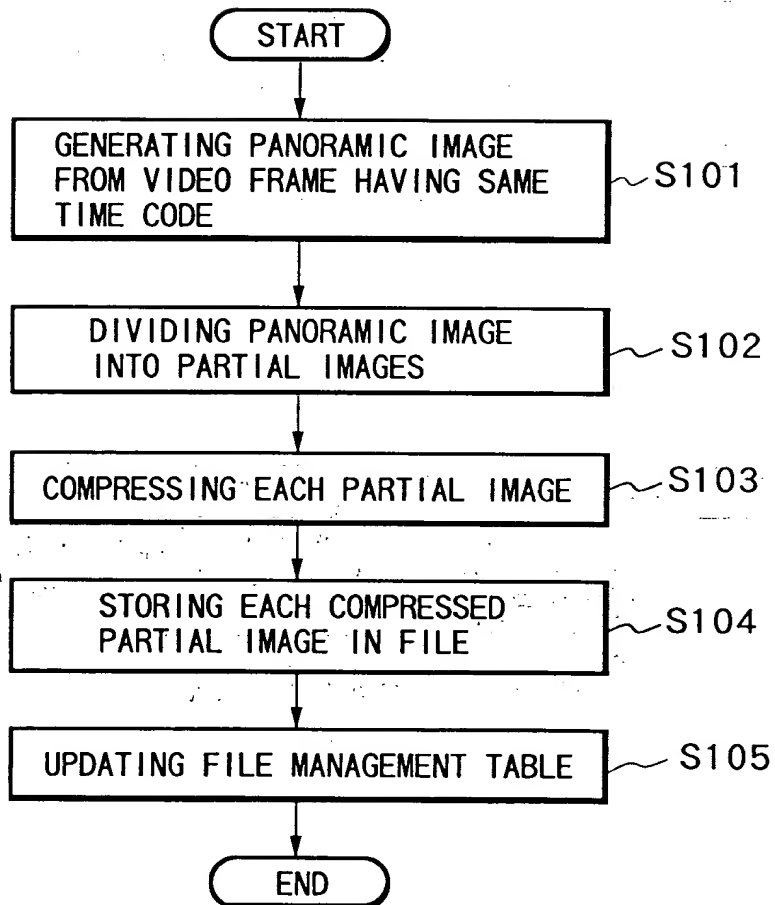


FIG. 11

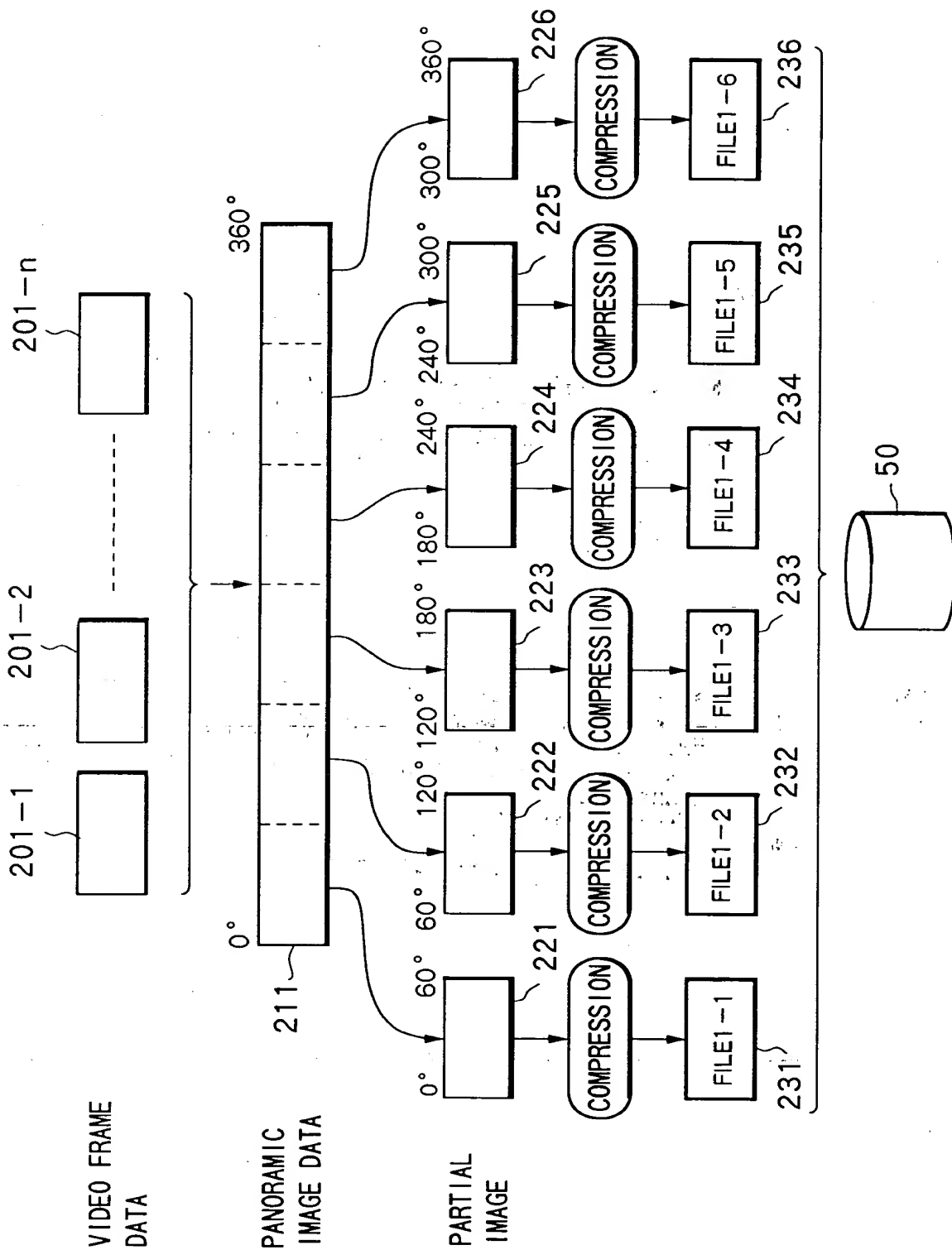


FIG.12

DIRECTION OF VIEWPOINT POSITION OF VIEWPOINT	0° ~ 60°	60° ~ 120°	120° ~ 180°	180° ~ 240°	240° ~ 300°	300° ~ 360°
	FILE1 - 1 FILE2 - 1	FILE1 - 2 FILE2 - 2	FILE1 - 3 FILE2 - 3	FILE1 - 4 FILE2 - 4	FILE1 - 5 FILE2 - 5	FILE1 - 6 FILE2 - 6

FIG.13

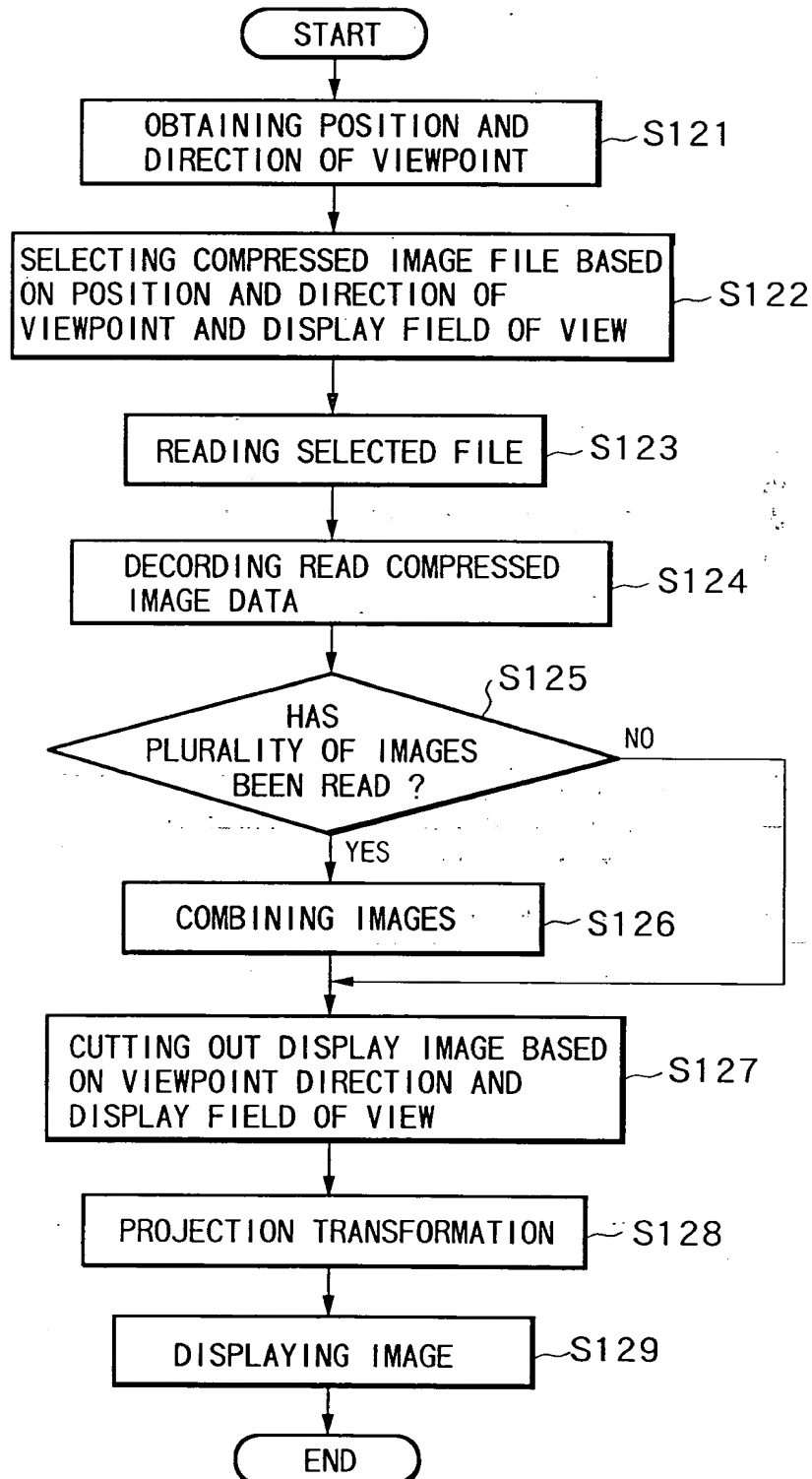


FIG.14

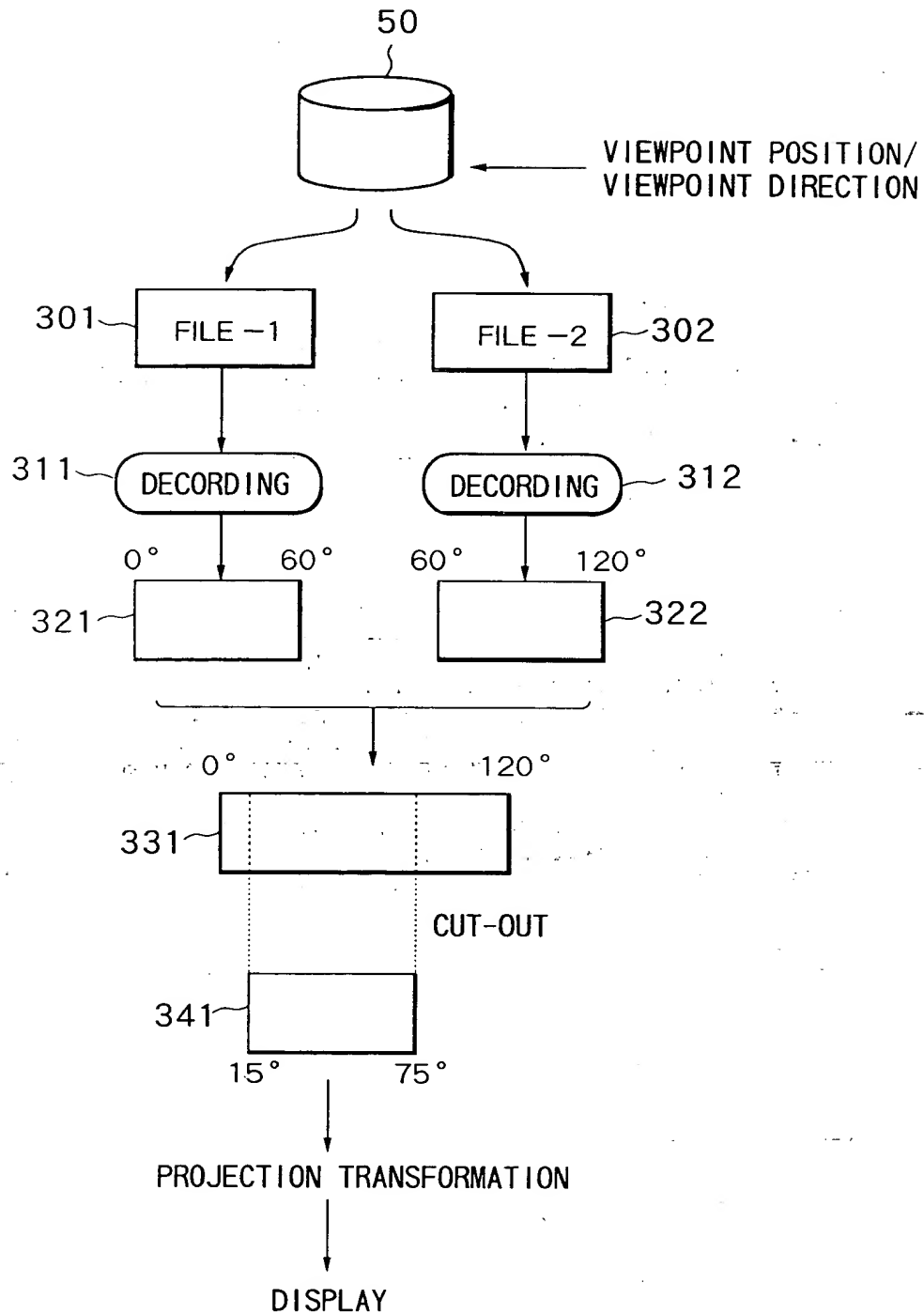


FIG.15A

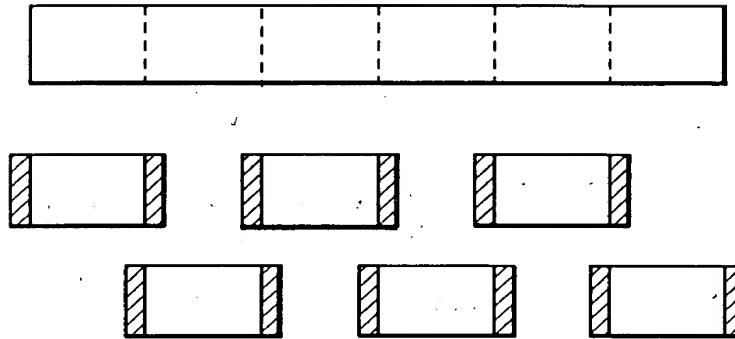


FIG.15B

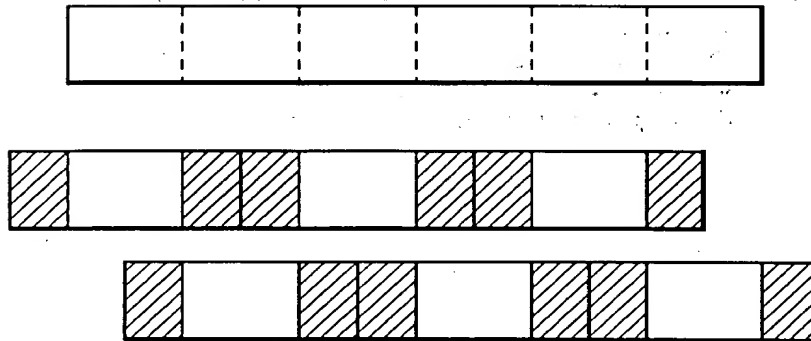


FIG.16

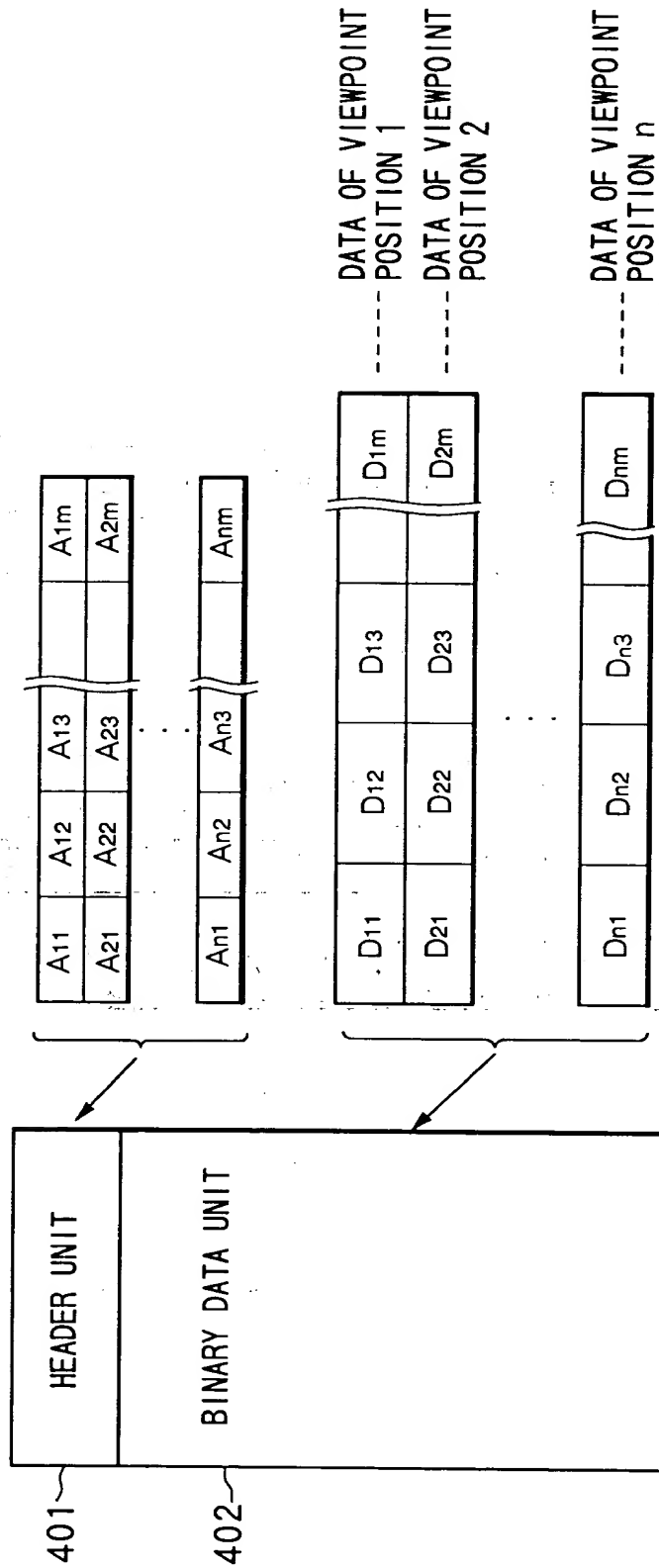




FIG.17

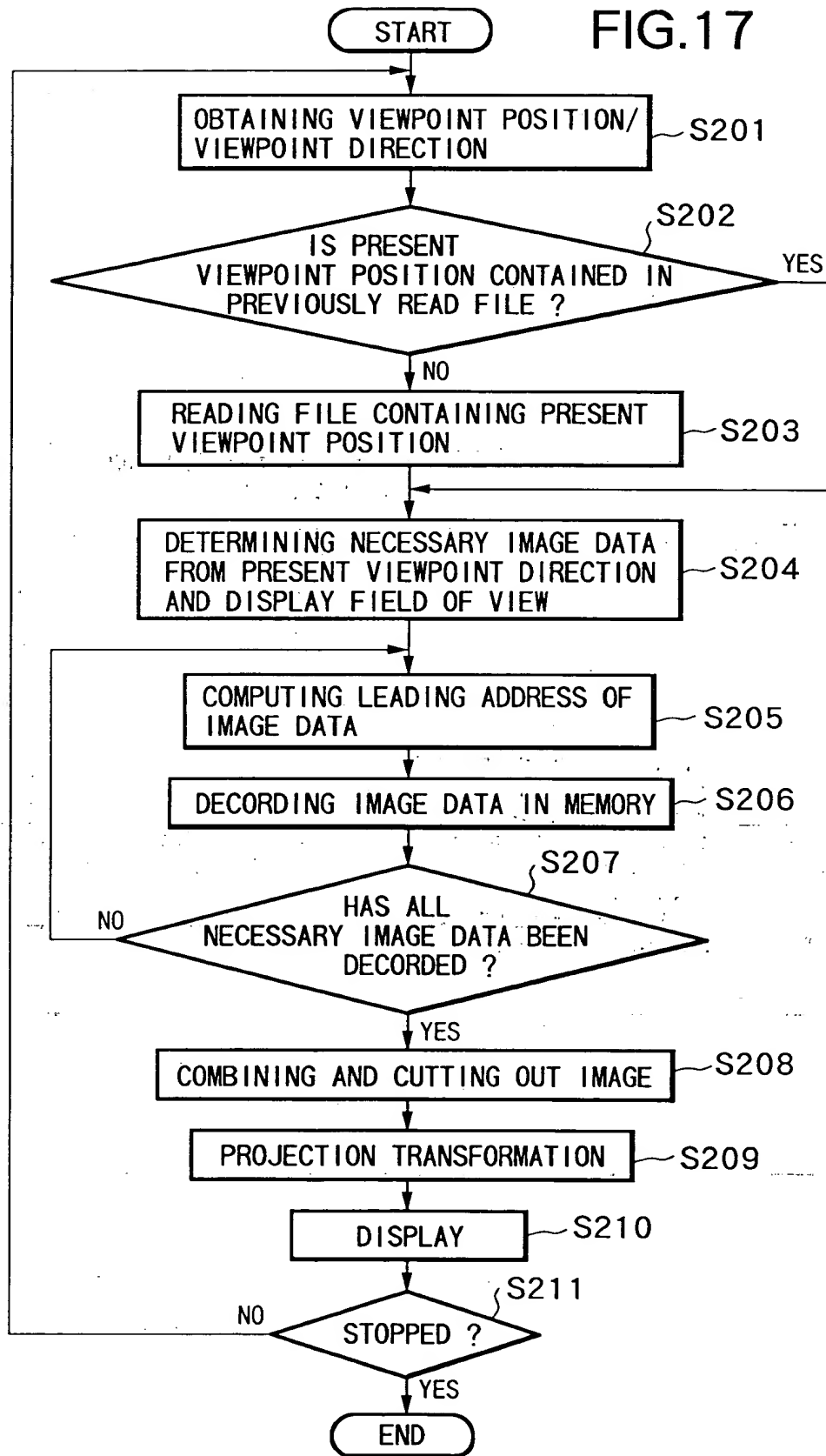


FIG.18A

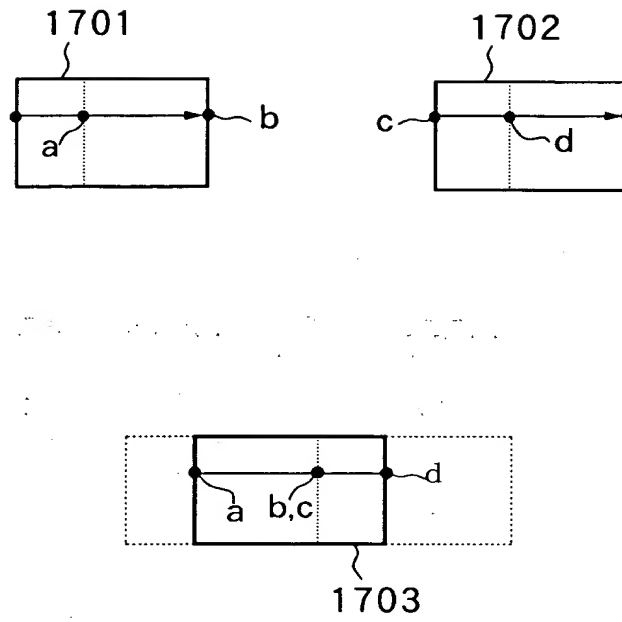


FIG.18B

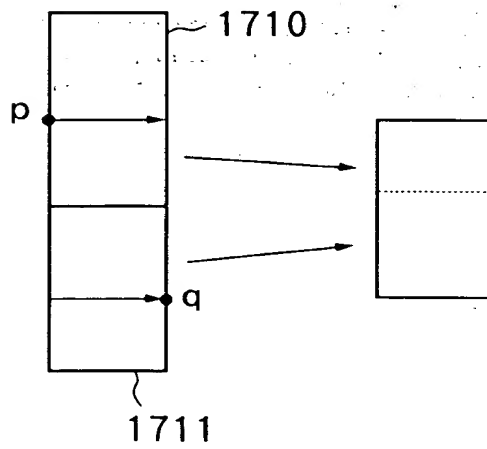


FIG.19

